TAYLOR SIMULATION AND EXPERIMENTAL INVESTIGATION OF ROLLING TEXTURES OF POLYCRYSTALLINE IRON ALUMINIDES WITH SPECIAL REGARD TO SLIP ON \{112\} PLANES

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(Received 17 January 1995; in revised form 31 May 1995)

Abstract—The evolution of the crystallographic rolling textures of B2- and DO3-ordered polycrystalline iron aluminides is described in terms of Taylor-type simulations. The contribution of crystallographic slip on the various types of glide systems, particularly the influence of \{112\}\{111\> slip is examined. The evolution of the aspect ratio of the grains during rolling is considered by gradually relaxing the externally imposed strain constraints with increasing deformation. For simulating low reductions, full constraints Taylor-type conditions are assumed. For describing intermediate reductions the lath model and for large reductions the pancake model is employed. The ratio of the critical resolved shear stress of the \{110\}\{111\> and \{112\}\{111\> slip systems is varied. The predictions yielded by impeding \{110\}\{111\> systems and promoting \{112\}\{111\> systems \((r_{110:111}=10 \times r_{112:111})\) are in good accord with experiment. The results are discussed in terms of the energy of the antiphase boundaries and of dislocation core effects.


1. INTRODUCTION

The mechanical properties as well as the excellent oxidation and sulfidation resistance of intermetallic iron aluminides with compositions near that of FeAl (B2) and Fe3Al (B2 or DO3) at low and elevated temperatures have long stimulated the research in this field [1–17]. The DO3 unit cell consists of four interpenetrating face centred cubic (f.c.c.) sublattices, one of which for the state of perfect order is occupied entirely by aluminium atoms. For perfect B2-type long-range order, two of the sublattices are occupied by aluminium atoms.

Especially, imperfectly B2 ordered Fe3Al based alloys are promising in industrial terms, e.g. Refs [13, 14]. The production of such Kurnakov-type compounds requires relatively small material costs. Furthermore, these alloys [11, 13, 14] reveal a better strength-to-weight ratio than some stainless steels. Due to the control of microstructure and composition, the corrosion resistance and the mechanical properties of Fe3Al-based alloys were considerably improved, especially the room temperature ductility and the strength at elevated temperatures [11–14].

Numerous studies have tackled the influence of ternary additions like Cr, Mo, Zr, Nb, Hf, C and B on the properties of these compounds [11–14]. Most of the alloys presently under investigation reveal a B2-type structure with perfect (FeAl) or imperfect (FeAl and Fe3Al containing up to 7 alloying elements) long-range order. Pure iron aluminides with more than 24 at % aluminium content usually reveal a DO3-type long-range order after slow cooling of only 10–20 K/day [8, 9, 11, 12, 18–20]. However, in the case of rapid cooling or thermomechanical treatment of iron aluminides with ternary additions, extensive primary solid solutions have been observed which include long-range ordered areas based
upon both the B2 and DO\textsubscript{3} structures, e.g. Refs [4, 8, 11–14].

For clarifying the underlying mechanisms of the strength and ductility of plastically deformed Fe\textsubscript{3}Al-based and comparable B2- or DO\textsubscript{3}-type alloys essentially two methods were employed in the past. First, the influence of the antiphase boundary (APB) energy was assessed on the selection of slip systems [5–12, 21–26]. Second, slip trace investigation on polished sample surfaces as well as transmission electron microscopy were employed [4–12, 21–25, 27–30]. In long-range ordered crystals, superlattice rather than ordinary lattice dislocations are the carriers of plastic deformation, e.g. Refs [11, 17]. The motion of imperfect superlattice dislocations gives rise to the generation of antiphase boundaries. In B2-ordered alloys two-fold dissociated and in DO\textsubscript{3} ordered alloys (Fe\textsubscript{3}Al and Fe\textsubscript{3}Si) two- and four-fold dissociated superlattice dislocation configurations were observed [11, 17, 31, 32]. Such dislocations are generated only when the magnitude of the externally imposed stress suffices to allow for production of the APB, e.g. Refs [7–11, 17, 21]. The presence of APB implies that superlattice dislocations cannot easily change their actual glide planes. It was shown that both the type of slip systems and the types of superlattice dislocations involved are determined by composition, temperature, strain rate and heat treatment prior to deformation, e.g. Refs [11, 17]. Consequently, these parameters revealed a considerable influence on the appearance of the slip line traces on polished sample surfaces (wavy or straight) [8, 9, 22–28]. The two types of slip line markings were usually interpreted in terms of deformation via ordinary (wavy) or superlattice (straight) dislocations. Concerning the active slip systems, it was shown that dislocation movement in perfectly or imperfectly B2- and DO\textsubscript{3}-ordered alloys at elevated temperatures essentially takes place on those glide systems, which are typically activated in non-ordered body centred cubic (b.c.c.) alloys [11, 17]. Whereas the occurrence of $\{110\}<111>$ slip systems seems to be promoted by their low APB energy, the strong tendency for $\{112\}<111>$ slip especially at low temperatures probably stems from dislocation core effects [15–17, 29]. Additionally, the activation of glide systems with a $<100>$ Burgers vector and $\{001\}$ or $\{111\}$ slip planes was predicted [11, 15–17, 22, 23, 30]. Although numerous, details of plasticity of iron aluminides were clarified by use of the techniques cited above, a quantitative assessment of the contribution of the various types of slip systems to large strain deformation was not yet achieved. Excellent reviews on this subject were recently submitted by McKamey et al. [11] and Umakoshi [17].

For the examination of plasticity of iron aluminides, especially at large strains, the employment of quantitative texture analysis [33, 34] seems to be a beneficial additional diagnostic tool for two reasons. Firstly, the evolution of the crystallographic texture during plastic deformation is directly connected with the displacement gradient tensor which results from the shear imposed by the active slip systems [35]. This close geometrical relationship between crystallographic slip on the one hand and the resulting grain orientations on the other hand enables one to employ textures as a probe for the determination of the slip systems which contribute to plastic deformation [35–37]. Secondly, the directional behaviour of poly-crystals is generally an integral property of their orientation distribution. Fe\textsubscript{3}Al based alloys with up to 5 mass% Cr content are considered as potential candidates for applications where ferritic stainless steels with about 17 mass% Cr are nowadays in use, e.g. Refs [11, 13, 14]. Consequently, their directional plastic properties, especially their deep drawing behaviour, should be studied. The first investigations about the crystallographic textures of deformed and heat-treated polycrystalline iron aluminides and comparable B2-ordered alloys were recently submitted by Mao and Sun [38, 39] and Raabe [40–42].

In the present study, the crystallographic textures which are developed during rolling of polycrystalline intermetallic FeAl- and Fe\textsubscript{3}Al-based B2- and DO\textsubscript{3}-ordered or partially-ordered aggregates are simulated by means of Taylor-type models. Special attention is drawn to the gradual relaxation of the externally imposed strain constraints with increasing deformation and to the critical resolved shear stress (CRSS) of the $\{110\}<111>$ and the $\{112\}<111>$ slip systems. The predicted orientation distributions are compared to experimental results.

2. SIMULATION METHOD

In the present study, the rolling textures of perfectly- and imperfectly-ordered iron aluminides are simulated by means of a Taylor-type model. Texture simulations according to Taylor [35] are based on the description of macroscopic deformation by means of crystallographic slip. The macroscopic deformation is characterised by the so-called distorsion or displacement gradient tensor written in lattice coordinates. Its symmetric part represents the strain tensor, while the antisymmetric part describes the resulting plastic rigid body rotation (not the grain rotation). From the latter tensor and the displacement gradient tensor written in machine coordinates the relevant orientation changes, i.e. the lattice rotations can be calculated, e.g. Refs [43–45].

The macroscopic deformation during rolling consists of elongation in rolling direction and thickness reduction parallel to the sheet plane normal, but no shears are involved. This strain tensor is referred to as an ideal plane strain tensor and will be used throughout the study. In the so-called full constraints (FC) Taylor-type approach [35] the imposed strain tensor is entirely transferred into each grain where it is fulfilled by crystallographic slip or twinning, respectively. Consequently, incompatibilities between
neighbouring grains are avoided. In the various variants of the so-called relaxed constraints (RC) Taylor-type approach [43, 46–48], however, some of the external shear components are not transferred into the grain, i.e., the relaxed constraints Taylor theory assumes that shear strains also occur microscopically. A relaxation of the strain component $\varepsilon_{13}$ corresponds to a shear in a longitudinal direction (so-called lath model), while $\varepsilon_{23}$ denotes transverse shear. The relaxation of both $\varepsilon_{13}$ and $\varepsilon_{23}$ is referred to as the pancake model. The axis convention is: 1 = rolling direction, 2 = transverse direction and 3 = normal direction. Allowing for these shears locally leads to distinct changes in the lattice rotation and thus in the texture development when compared to the predictions by FC theory.

The evolution of the aspect ratio of the grains during rolling is taken into account by gradually relaxing the externally imposed strain constraints with increasing deformation. For simulating low reductions, FC Taylor-type conditions are stipulated. For describing intermediate reductions, the lath model, and for large reductions, the pancake model are employed (Table 1). As was pointed out by Raphanel and van Houette [48] this successive relaxation scheme is to a certain extent arbitrary. In the current study, hence, the influence of the relaxation scheme on the simulation results was examined. For this purpose three modes of subsequent relaxation of $\varepsilon_{13}$ and $\varepsilon_{13} + \varepsilon_{23}$ were used. According to scheme 1, FC conditions were employed up to a total reduction of $\varepsilon = 10\%$, lath conditions between $\varepsilon = 10$ and 30% and the pancake model within the range $\varepsilon = 30$–90%. In scheme 2, the FC model was applied up to $\varepsilon = 30\%$, the lath model between 30 and 70% and the pancake model within the range $\varepsilon = 70$–90%. According to scheme 3, the FC model was used up to a reduction of $\varepsilon = 30\%$ and the pancake model within the range $\varepsilon = 30$–90% (Table 1). In this context $\varepsilon$ denotes the reduction $\varepsilon_{13}$.

For the fulfilment of the imposed strain tensor $\{110\}<111>$ and $\{112\}<111>$ slip systems were considered in accordance with results stemming from single crystal experiments, e.g., Refs [11, 15–17]. As was shown previously for non-ordered body centred cubic (b.c.c.) alloys [48], the asymmetry of $\{112\}<111>$ slip is of minor importance and was hence neglected. For the selection of the active slip systems in the case of non-unique solutions, the second-order plastic criterion suggested by Renouard and Wintenberger [49] was applied. In contrast to former studies [40–42] the ratio of the critical resolved shear stress (CRSS) on both systems $\lambda = \tau_{\{110\}<111>}/\tau_{\{112\}<111>}$ was varied within the range 10–1. In the present study, the

![Figure 1](image_url)

**Fig. 1.** Schematic presentation of some relevant texture components observed in rolled B2- and DO2-ordered iron aluminides [38–42] and non-ordered b.c.c. metals and alloys [35, 50–52]. The textures are presented by using $\{200\}$ pole figures [Fig. 1(a)] and three ODF sections, $\phi_1 = 0^\circ$, $\phi_1 = 60^\circ$ and $\phi_1 = 90^\circ$ [Fig. 1(b)].
CRSS represents a somewhat artificial value. However, comprising various influences like the nucleation of superlattice dislocations, core effects and the Peierls stress [15–17], it represents a rough measure of whether dislocations on a certain glide system contribute to slip or not. In the Taylor model employed it is not practicable to explicitly differentiate between deformation via ordinary or superlattice dislocations. This is due to the fact that in the Taylor theory, the slip systems are reduced purely to their geometrical function, i.e. the entire framework of dislocation dynamics is completely neglected. Whereas the influence of the changing aspect ratio of the grains is artificially treated by the RC-type models, the absence of dislocation dynamics implies that effects like strain hardening, the influence of the cell sizes and the occurrence of mesoscopic inhomogeneities like micro- and shear-bands which all affect the texture development in terms of quantitative (rotation velocity, texture maximum) and qualitative deviations (stable orientations) are not taken into consideration. Consequently, the present study does not tackle the question of whether the activation of ordinary or superlattice dislocations prevails during deformation. However, it investigates whether the carriers of plastic deformation move primarily on {110} or {112} slip.
The simulation was carried out by the use of 936 initial randomly-distributed single orientations. For computing the resulting 3-D orientation distribution function (ODF) each orientation was superimposed by a Gauss function with a scatter width of $7^\circ$ [34]. From the ODEs the centrosymmetric 2-D $(200)$ pole figures were additionally projected. Pole figures do not allow presentation of all relevant details of the 3-D textures because of the superposition of the types of poles considered. However, they adequately represent the main features of the texture and are thus helpful in qualitative terms.

Rolled b.c.c., e.g. Refs [50–52] and most related B2- and DO$_3$-ordered alloys [38–42] typically develop strong fibre textures. Their main features can conveniently be presented using pole figures [Fig. 1(a)] or some important isointensity diagrams ($\phi_2$-sections) of the ODF [Fig. 1(b)]. In this study the textures are presented by using both $(200)$ pole figures [Fig. 1(a)] and three main ODF sections, $\phi_1 = 0^\circ$, $\phi_1 = 60^\circ$ and $\phi_1 = 90^\circ$ [Fig. 1(b)].

Relevant texture components which are typically generated during rolling are positioned on the so-called $x$-fibre which comprises all orientations with a common crystallographic $\langle 110 \rangle$ direction parallel to the rolling direction (e.g. $\{001\} \langle 110 \rangle$ at $\phi = 0^\circ$, $\phi_1 = 0^\circ$, $\langle 112 \rangle \langle 110 \rangle$ at $\phi = 35^\circ$, $\phi_1 = 0^\circ$ and $\langle 111 \rangle \langle 110 \rangle$ at $\phi = 55^\circ$, $\phi_1 = 0^\circ$) and on the so-called $y$-fibre.

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Fig. 3. Simulated development of rolled B2- and DO$_3$-ordered iron aluminides according to scheme (b (Table 1): $\langle 110 \rangle \langle 111 \rangle$ and $\langle 112 \rangle \langle 111 \rangle$ slip, $\tau_{\langle 110 \rangle \langle 111 \rangle} = 10 \times \tau_{\langle 112 \rangle \langle 111 \rangle}$, gradual strain relaxation: $\epsilon = 0$–10% (FC), $\epsilon$ $\geqslant$ 10–30% (RC, lath), $\epsilon$ $\geqslant$ 30–90% (RC, pancake). Presentation as [200] pole figure and ODF using relevant $\phi_1$-sections: (a) $\epsilon = 30\%$; (b) $\epsilon = 60\%$; and (c) $\epsilon = 80\%$ ($\epsilon = \epsilon_1$).
3. SIMULATION RESULTS

Two simulations were conducted according to scheme 1 (Table 1). The first one with a = 1, hereafter referred to as scheme 1a simulation, is depicted in Fig. 2. The second one with a = 10, hereafter referred to as scheme 1b simulation, is shown in Fig. 3. According to scheme 1a the formation of a uniform γ-fibre containing orientations with a common {111} plane parallel to the surface of the sheet, i.e. {111}{110} at φ₁ = 0°, 60° and {111}{112} at φ₁ = 30°, 90° [Fig. 1(b)] [38-42, 50-52].

According to scheme 1b the formation of a uniform α-fibre ranging from a slightly pronounced {001}{110} (φ₁ = 0°, φ = 0°, φ₂ = 45°) to nearly {111}{110} (φ₁ = 0°, φ ≈ 55°, φ₂ = 45° and φ₁ = 60°, φ ≈ 55°, φ₂ = 45°) accompanied by a {111}{112} (φ₁ = 90°, φ ≈ 55°, φ₂ = 45°) on the γ-fibre is revealed for ε ≈ 60% [Figs 2(a, b)]. For ε = 80% on the equally shaped α-fibre, two maximum components, one at {001}{110} and one close to {111}{110} at φ ≈ 48° are generated. On the γ-fibre the maximum is stabilised at {111}{110}, whereas {111}{112} is degraded [Fig. 2(c)].

Scheme 1b simulation leads to a different prediction (Fig. 3). At low reductions [Fig. 3(a)] a uniform
α-fibre and a very weak γ-fibre are formed. At elevated reductions [Figs 3(b, c)], two isolated components are formed on the α-fibre, whilst the γ-fibre, especially the {111}⟨112⟩, is completely degraded. At reductions within the range ε = 60–80% the first strong maximum is located close to {001}⟨110⟩ and the second one close to {223}⟨110⟩ [Fig. 3(c)].

The two simulations which were conducted in accord with scheme 2 are named scheme 2a (λ = 1) and scheme 2b (λ = 10) simulation [Figs 4, 5]. At low reductions, ε = 30% [Figs 4(a), 5(a)], both simulations predict a uniform α-fibre ranging from {001}⟨110⟩ to a slightly pronounced {111}⟨110⟩ and a γ-fibre. At larger reductions, scheme 2a simulation leads to a non-uniformly shaped α-fibre with a maximum at {112}⟨110⟩ which is accompanied by a {111}⟨112⟩ component on the γ-fibre [Figs 4(b, c)]. In the same regime (ε = 60 and 80%) the scheme 2b model predicts a strong maximum close to {112}⟨110⟩ and the total decrease of the γ-fibre, especially of the {111}⟨112⟩ orientation [Figs 5(b, c)].

The two simulations which were executed following scheme 3 are hereafter referred to as scheme 3a (λ = 1) and scheme 3b (λ = 10) models, respectively (Figs 6, 7). Employing, scheme 3a's approach, a uniformly shaped α-fibre with a maximum at

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Fig. 5. Simulated development of rolled B2- and DO3-ordered iron aluminides according to scheme 2b (Table 1): {110}⟨111⟩ and {112}⟨111⟩ slip, \( t_{1(011)} = 10 \times t_{(111)} \), gradual strain relaxation: \( ε = 0–30% \) (FC), \( ε = 30–70% \) (RC, lath), \( ε = 70–90% \) (RC, pancake). Presentation as {200} pole figure and ODF using relevant \( φ_1 \)-sections: (a) \( ε = 30% \); (b) \( ε = 60% \); and (c) \( ε = 80% \) (\( ε = t_{1(1)} \)).
{[111]<110>} is predicted (Fig. 6). On the regularly formed γ-fibre an orientation tube ranging from the pronounced {111}<110> orientation to a weaker component close to {111}<112> is revealed (Fig. 6). The scheme 3b simulation (Fig. 7) bears a certain resemblance to the scheme 1b prediction (Fig. 3). At low reductions [Fig. 7(a)], a uniform α-fibre and a weak γ-fibre are generated. At larger reductions [Figs 7(b, c)] two single components are formed on the α-fibre whilst the γ-fibre, especially the {111}<112>, is weakened. At ε = 80% one strong maximum is located close to {001}<110> and a second one between {223}<110> and {111}<110> [Fig. 7(c)].

4. EXPERIMENTAL PROCEDURE AND RESULTS

A cast intermetallic Fe₃Al alloy with 15.7% Al, 0.088% Cr, <0.05% Zr, 0.02% Mo and 0.06% C (% = mass%) was thermomechanically hot rolled to a final thickness of 4.86 mm and finally annealed at 870 K. The latter two manufacturing steps are referred to as B2 treatment [13, 14]. Subsequently, the sheet was rolled at 800–830 K to ε = 80%. The final sheet had an imperfectly-oriented B2 structure [13, 14]. Recrystallisation was not observed. The microstructure of the rolled samples was studied by means of optical and electron microscopy. For this
purpose the specimens were etched in pure HCl (1–3 min) in the case of low deformation and in a solution of 10 ml H₂O₂ and 1 ml HF (30 s) in the case of large reductions (ε ≥ 70%).

The textures were measured in the centre layer of the specimens. For this purpose the samples were ground and finally etched by use of pure HCl. The experiments were carried out on an X-ray texture goniometer using MoKα radiation. The four incomplete pole figures: {220}, {400}, {422} and {620} were measured within the range of the pole distance angle x = 5°–85° in the back reflection mode [53]. From the 2-D, centrosymmetric pole figures the quantitative 3-D ODF was computed using the iterative series expansion procedure (Iₘₐₓ = 22) [54–56].

Figure 8 shows the starting texture, i.e. the orientation distribution after casting, thermomechanical hot rolling and final heat treatment. The maximum occurring orientation density is quite small, f(g)ᵢₘₐₓ = 6.8. The ODF reveals two main initial texture components, viz. an orientation located between the {112}⟨110⟩ and the {111}⟨110⟩ component, and a {001}⟨110⟩ orientation. Additionally, a weak γ-fibre appears. In the corresponding microstructure essentially equiaxed or slightly elongated grains were found which suggests that recrystallisation has taken place during or subsequent to the thermomechanical treatment (Fig. 9).

After 30% reduction the texture reveals a dominant component close to {111}⟨100⟩, a weak

Fig. 7. Simulated development of rolled B₂ and DO₂-ordered iron aluminides according to scheme 3b (Table 1): {110}⟨111⟩ and {112}⟨111⟩ slip. τᵢ(110/111) = 10 × τᵢ(112/111), gradual strain relaxation: ε = 0–30% (FC), ε ≥ 30–90% (RC, pancakes). Presentation as {200} pole figure and ODF using relevant φ₂-sections: (a) ε = 30%; (b) ε = 60%; and (c) ε = 80% (ε = εₙ₁).
{001}<110> orientation and an equally shaped γ-fibre consisting of {111}<110> and {111}<112> [Fig. 10(a)]. The {112}<110> orientation which was inherited from the starting texture rotated towards the {111}<110> component. This type of texture, especially the minimum at {112}<110> is typical of rolling textures of B2-ordered alloys [38–42]. However, it is not typical of rolled non-ordered b.c.c. compounds which reveal a texture maximum at {112}<110> rather than a minimum [50–52].

With increasing rolling deformation, \( \epsilon = 60\% \) [Fig. 10(b)] and \( \epsilon = 80\% \) [Fig. 10(c)], the γ-fibre gradually increases. The orientation density of the {001}<uvw> texture fibre, especially of the {001}<110> component remains very weak. The formation of a {111}<uvw> texture fibre is well known from cold-rolled non-ordered b.c.c. alloys [50–52]. However, at large strains in these materials the γ-fibre is accompanied by an equally shaped α-fibre, especially by a {001}<110> and a dominant {112}<110> component. The rolled Fe₃Al specimen reveals a weak {001}<110> orientation, but the {112}<110> component does not appear at all. Although an orientation close to {112}<110> was present in the initial texture (Fig. 8) it decreases during subsequent cold rolling rather than stabilises (Fig. 10).

5. DISCUSSION

The Taylor simulations (Figs 2–7) can either be discussed in terms of the type of gradual strain relaxation (Table 1) or in terms of the ratio of the critical resolved shear stress (CRSS) on both systems \( \lambda = \tau_{110}(112)/\tau_{112}(111) \) which was either 1 or 10. From the simulation results, the latter approach is suggested. Both the simulations which were carried out with \( \lambda = 1 \) (Figs 2, 4, 6) and with \( \lambda = 10 \) (Figs 3, 5, 7) bear a strong resemblance among each other. The first group containing scheme 1a (Fig. 2), scheme 2a (Fig. 4) and scheme 3a (Fig. 6) approaches is hereafter named type A simulation (\( \lambda = 1 \)). The second group containing scheme 1b (Fig. 3), scheme 2b (Fig. 5) and scheme 3b (Fig. 7) approaches is
hereafter named type B simulation ($\lambda = 10$). The textures predicted by the type A approach ($\tau_{[100]<[110]} = \tau_{[111]<[110]}$) reveal the following common characteristics:

**Type A.** The $x$-fibre reveals a fairly homogeneous shape between $\{001\}<110>$ and $\{112\}<110>$ (Fig. 4) or $\{111\}<110>$, respectively (Figs 2, 6). The $y$-fibre reveals a quite homogeneous shape with a maximum either at $\{111\}<110>$ (Figs 2, 6) or at $\{111\}<112>$ (Fig. 4). The maximum occurring orientation densities after $\epsilon = 80\%$ are within the range $f_{\text{max}} = 15.5 - 18.3$, i.e. they are generally lower than for the type B simulations. The textures predicted bear a considerable resemblance to the textures of non-ordered b.c.c. alloys [50–52]. The relaxation schemes employed seem to be of secondary importance. However, the approaches which make use of the pancake model already at low strains, $\epsilon \geq 30\%$, viz. scheme 1 (Fig. 2) and scheme 3 (Fig. 6), yield a somewhat better agreement with b.c.c. rolling textures [50–52] than the scheme 2 approach (Fig. 4). From the analysis of the amount of shear contributed by the various types of slip systems it is revealed that orientations close to $\{112\}<110>$ and $\{111\}<112>$ are essentially stabilised by $\{110\}<111>$ slip systems. Orientations close to $\{001\}<110>$ and $\{111\}<110>$ are stabilised by both $\{110\}<111>$ and $\{112\}<111>$ glide systems.

![Figure 10](#)

Fig. 10. Experimental rolling textures in the centre layer ($T_{\text{cool}} = 800–830\, \text{K}$), orientation distribution function (ODF) calculated by use of the iterative series expansion method ($J_{\text{max}} = 22$) [54–56]. Presentation as $\{200\}$ pole figure and ODF using relevant $\phi_1$-sections: (a) $\epsilon = 30\%$; (b) $\epsilon = 60\%$; and (c) $\epsilon = 80\%$ ($\epsilon = \epsilon_\ell$).
In contrast, the textures predicted by the type B approach \( \langle \{110\}\langle110\rangle = 10 \times \langle \{112\}\langle111\rangle \rangle \) are all characterised by the following features:

**Type B.** The \( x \)-fibre is not uniformly shaped but reveals two distinct maximum components, one close to \{001\}\langle110\rangle and one close to \{112\}\langle110\rangle (Fig. 5) or \{223\}\langle110\rangle, respectively (Figs 3, 7). The \( y \)-fibre is usually very weak (Fig. 5) or reduced to a weak component close to \{111\}\langle110\rangle (Figs 3, 7). The maximum occurring orientation densities after \( \varepsilon = 80\% \) are in all cases higher than for the type A simulations. They are within the range \( f(x)_{\text{max}} = 23.2-35.6 \). The textures predicted bear little resemblance to the textures of non-ordered b.c.c. alloys [50–52]. The formation of a strong \{001\}\langle110\rangle texture component is promoted by the dominance of \{112\}\langle111\rangle slip. The relaxation schemes employed seem to be of minor relevance. Due to the high CRSS on the \{110\}\langle111\rangle slip systems the shear is exclusively contributed by the \{112\}\langle111\rangle slip systems.

From the features discussed above it appears that the type B approach (\{112\}\langle111\rangle slip planes), especially schemes 1b and 3b, yields a better agreement with experiment (Fig. 10) than the type A approach (\{110\} and \{112\} slip planes). Although the orientation density of the \{001\}\langle110\rangle and of the \{111\}\langle112\rangle component is not correctly predicted at large reductions (Figs 3, 7) the absence of the \{112\}\langle110\rangle orientation which usually dominates the rolling textures of non-ordered b.c.c. alloys [50–52] seems to be an important indicator for the prevalence of the \{112\}\langle111\rangle slip. The \{112\}\langle110\rangle component is stabilised by pure \{110\}\langle111\rangle slip and generally destabilised by pure \{112\}\langle111\rangle slip. This is not only shown by the complex models employed in this study but also covered by a simple Sachs type approach [57] under double slip conditions. Applying the latter model with pure \{112\}\langle111\rangle slip predicts a \{332\}\langle110\rangle component. This solution approximately corresponds to the stable orientation between \{223\}\langle110\rangle and \{111\}\langle110\rangle which is predicted by two type B simulations (Figs 3, 7) and which is observed experimentally (Fig. 10). Whereas a typical b.c.c. rolling texture contains two fibres, viz. \( x \)- and \( y \)-fibres, the typical B2 or, respectively, DO1 texture only contains one fibre, namely the \( y \)-fibre or at least a fibre close to that (so-called \( \beta \)-fibre). Since the crystallographic texture is directly connected to the activated slip systems it may hence be concluded that \{110\}\langle111\rangle glide systems do not play the leading role for the plastic deformation of B2 and DO1 ordered polycrystals.

However, this observation does not mean that plastic deformation of such compounds is exclusively attained by activation of \{112\}\langle111\rangle glide systems. This qualification is supported by the evolution of the orientation density of both the \{001\}\langle110\rangle and of the \{111\}\langle112\rangle texture components. Their development during rolling (Fig. 10) is not adequately covered by the scheme B simulations (Figs 3, 7). Whereas the orientation density of the \{001\}\langle110\rangle component is overestimated by the type B models, that of the \{111\}\langle112\rangle component is underestimated when compared to the experiment (Fig. 10). This observation substantiates that \{110\}\langle111\rangle glide systems may indeed contribute at least a minor portion to the deformation of certain texture components. As will be discussed at the end of this section, such transition between both types of slip as a function of temperature, strain rate and grain orientation is also conceivable from an atomistic point of view.

The second result which requires some consideration is the influence of the various relaxation schemes on the resulting texture (Table 1). It is evident that the incorporation of the pancake model already at low reductions, \( \varepsilon > 30\% \), scheme 1 (Fig. 3) and scheme 3 (Fig. 7) leads to a better agreement with experiment than its incorporation at large reductions, \( \varepsilon > 70\% \) (Fig. 5). At first sight this indicates a strong influence of the grain shape. However, Fig. 9 shows that the aspect ratio of the initial grains (\( \varepsilon = 0\% \)) is close to 1, i.e. the crystals are only slightly elongated at low reductions. Furthermore, the consideration of grain shape via successive relaxation of strain constraints is generally a coarse approximation and to a certain extent arbitrary. For any sound physical approach which aims to incorporate local strain relaxation, the local texture and morphology must be known [58, 59]. Consequently, in the present case an argumentation in terms of morphology is not convincing.

However, the relaxation of two strain constraints, viz. of \( \varepsilon_{11} \) and \( \varepsilon_{21} \), leads to a decrease in the number of active slip systems from five to three. This results in the degradation of the corresponding deformation energy, which is computed by \( \tau_{112,113}; M \), where \( \tau_{112,113} \) is the CRSS on \{112\}\langle111\rangle slip systems and \( M \) the Taylor factor. In a rough approach, the local accomplishment of shear strains between two neighbouring grains may be regarded in terms of two conflicting energies. The first one is the gain of energy that is achieved by relaxing strains locally. The decrease of the number of active slip systems from 5 (FC) to 3 (RC) leads to a degradation of the corresponding Taylor energy. This portion is described by the difference of the deformation energy predicted by the FC and RC models, i.e.

\[
\varepsilon \cdot (M_{\text{FC}} - M_{\text{RC}})
\]

The gain in deformation energy is hence linearly proportional to the CRSS. However, the relaxation of strain constraints locally may lead to geometrical incompatibility between the grains. The competitive term which must hence be balanced by the gain in Taylor energy is the elastic energy which is required to compensate this incompatibility. It may be described as non-localised in terms of an elastic strain accommodation energy [60] or localised in terms of geometrically necessary dislocations [58, 61]. Due to this balance it is conceivable that if the CRSS increases, e.g. through the generation of
ABP, and if the elastic accommodation energy remains unchanged, it is energetically more favourable to decrease the number of active slip systems, i.e. to relax strain constraints locally, than to avoid incompatibilities by activating five slip systems. Such argument seems physically reasonable since in ordered alloys a large glide resistance, i.e. a large Taylor energy must be considered due to the energy of the APB, core effects and the Peierls stress [8, 15–17]. The presence of superlattice dislocations in the deformed samples is indeed suggested by the slip traces which were observed in the longitudinal sections of many grains (Fig. 11). These traces were usually straight rather than wavy [8, 11, 17, 31, 32].

Finally, a third argument, namely the starting texture must be taken into account when discussing the success of the pancake-type models. From Fig. 8 it is evident that some important features of the final texture (Fig. 10) are already present prior to the final rolling procedure. The initial texture maximum close to $[112][110]$ which is not stable under $[112][111]$ slip conditions has a disorientation of about $15^\circ$ with respect to the $[111][110]$ orientation and about $30^\circ$ with respect to the $[111][112]$ orientation. It is likely that the initial $[112][110]$ texture component rotates towards the $[111][110]$ orientation and hence additionally promotes the increase of the $\gamma$-fibre during rolling.

Concluding prevalence of $[112][111]$ rather than of $[110][111]$ slip from the comparison of predicted and experimentally observed textures represents a phenomenological approach. A supplementary direct result was achieved by the employment of single orientation determination in the SEM [62, 63]. By determination of the vectors of the slip markings together with the grain orientation the traces of the slip planes were computed in lattice coordinates. In these experiments a large portion of $[112]$ slip planes and a minor contribution of $[110]$ slip planes were identified. A thorough analysis of the data will be given in a subsequent paper.

Finally, it remains an open question why $[112][111]$ slip prevails whilst $[110][111]$ slip is impeded. The generation and the movement of superlattice dislocations in B2- and DO$_2$- ordered alloys with a constant order parameter is essentially governed by two lattice properties. First, by the energy of the APB, which affects the nucleation and interaction [8–10, 21] and second, by the dislocation core structure [15–17, 29] which affects the mobility of superlattice dislocations. Following Umakoshi et al. [15–17] and Takeuchi [29] the dislocation core of superpartials in the B2 lattice has a similar structure as in ordinary screw dislocations in the b.c.c. lattice. That means in the case of $[110][111]$ superlattice dislocations the cores of the corresponding superpartials are extended on three intersecting $[110]$ planes where they create faults. The cores are oriented in such a way that they do not overlap the APB. As in non-planar b.c.c. dislocations the three intersecting $[110]$ layer faults extend on the $[112]$ planes at their tips. As reported by Umakoshi et al. [15–17], the energy of the APB of $a/2[110][111]$ dislocations is lower compared to $a/2[112][111]$ superpartials. However, their core is most likely more extended than that of $a/2[112][111]$ dislocations. For the movement, the dislocation core must therefore first be converted into a planar configuration which increases the glide resistance. In contrast, $a/2[112][111]$ superpartials create intricate multi-layer faults which advocate the assumption that their dislocation cores are smaller. Although they have a higher APB energy than $[110][111]$ dislocations their cores can easily transform into a glissile configuration prior to the net
movement. This causes an altogether lower glide resistance compared to the \( a[\{110\}\langle111\rangle] \) dislocations. It is thus assumed that the strong tendency for \( \{112\} \langle111\rangle \) slip cannot be interpreted in terms of the APB energy but in terms of dislocation core effects [15–17].

6. CONCLUDING REMARKS

The texture evolution during rolling of B2- or DO2-ordered polycrystalline iron aluminides was described by Taylor-type simulations and compared with experimental results. In the simulations, \( \{110\}\langle111\rangle \) and \( \{112\}\langle111\rangle \) slip systems were considered. The ratio of the CRSS on both systems \( \lambda = \tau_{\{110\}\langle111\rangle}/\tau_{\{112\}\langle111\rangle} \) was assumed to be 1 or 10, respectively. The evolution of the grain shape during rolling was considered by gradually relaxing the external strain constraints with increasing deformation. The simulations with \( \lambda = 10 \) (activation of \( \{112\} \) slip planes) yielded a better agreement with experiment than the simulations with \( \lambda = 1 \) (activation of \( \{110\} \) and \( \{112\} \) slip planes). The predominance of \( \{112\}\langle111\rangle \) slip was discussed in terms of the energy of the APB and of dislocation core effects. The incorporation of the pancake model already at low reductions, \( \epsilon \geq 30\% \) showed a better correspondence to experiment than its incorporation at large reductions, \( \epsilon \geq 70\% \). The accomplishment of strain by only three slip systems was attributed to the large glide resistance in ordered alloys. It was assumed that it is energetically more favourable to decrease the number of active slip systems than to avoid strain incompatibilities.

Acknowledgements—The author gratefully acknowledges the kind support by the University of Science and Technology, Beijing, China, especially by Professor Dr Z. Sun and Professor Dr W. Mao. The FeAl alloy used in this study was cast and thermomechanically processed at the Department of Materials Science and Engineering at the University of Science and Technology, Beijing.

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