# Microstructure Mechanics Crystal Mechanics

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## **Contact, website and class days**



Date / Location	Topics	Lecturer
15. April 2016 IMM / RWTH	Introduction to materials micromechanics, multiscale problems in micromechanics, case studies, crystal structures and defects, relation to products and manufacturing	Raabe
22. April 2016 IMM / RWTH	Crystal structures, dislocation statics, crystal dislocations, dislocation dynamics	Raabe
29. April 2016 IMM / RWTH	Dislocations, crystalline anisotropy and crystal mechanics in hexagonal metals	Sandlöbes
6. May 2016 IMM / RWTH	No classes	-
13. May 2016 IMM / RWTH	Fracture mechanics Introduction to FEM	Shanthraj
20. May 2016 IMM / RWTH	Athermal phase transformations in micromechanics	Wong
27. May 2016 IMM / RWTH	No classes	-
3. June 2016 IMM / RWTH	Crystal micromechanics, single crystal mechanics, yield surface mechanics, polycrystal models, Taylor model, Integrated micromechanical experimentation and simulation for complex alloys, hydrogen embrittlement	Raabe
10. June 2016 IMM / RWTH, 12:15	Micromechanics of polymers and biological (natural) composites	Raabe
17. June 2016 IMM / RWTH, 12:15	Applied micromechanics: multiphase and composite material design	Springer





- Single crystal yield surface
- Empirical yield surface
- Taylor model for the mechanics of polycrystals
- Examples

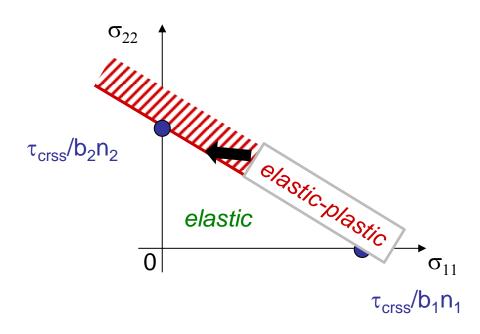


Yield criterion for single slip:

$$\sigma_{ij}\,b_i\,n_j=\tau_{\rm crss}$$

• In 2D this becomes  $(\sigma_1 \equiv \sigma_{11})$ :

$$\sigma_{11} b_1 n_1 + \sigma_{22} b_2 n_2 = \tau_{crss}$$





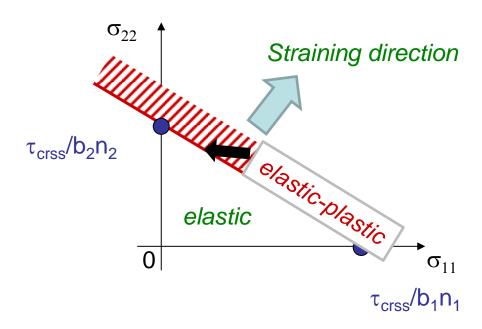
What is the straining direction? The strain increment is given by:

$$d\varepsilon = \Sigma_{s} d\gamma^{(s)} b^{(s)} n^{(s)}$$

2D case:

$$d\varepsilon_1 = d\gamma b_1 n_1; d\varepsilon_2 = d\gamma b_2 n_2$$

vector perpendicular to the line for yield

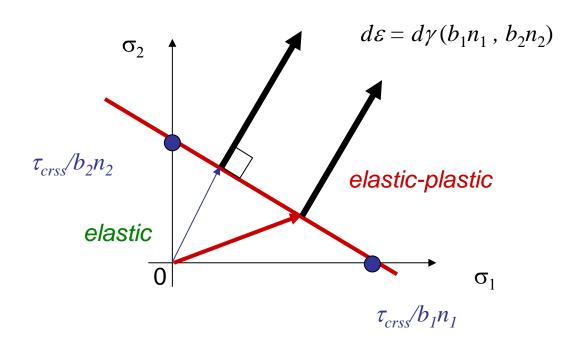




straining direction in stress space

normality rule for crystallographic slip

Any given stress state can in a crystal in large-strain elasto-plasticity act only in the form of shear (except hydrostatic effects)





## slip system s

$$n_{\scriptscriptstyle i}^{\scriptscriptstyle g}$$
 ,  $b_{\scriptscriptstyle i}^{\scriptscriptstyle g}$ 

#### orientation factor for s

$$m^{\mathfrak s}_{ij} = n^{\mathfrak s}_i \, b^{\mathfrak s}_j$$

symmetric part

$$m_{ij}^{\text{sym,s}} = \frac{1}{2} (n_i^s b_j^s + n_j^s b_i^s)$$

rotate crystal into sample

$$m^{\mathfrak s}_{kl} = a^{\mathfrak c}_{ki} n^{\mathfrak s}_i \ a^{\mathfrak c}_{lj} b^{\mathfrak s}_j$$

 $\sigma_{33}/ au_{
m mit}$ 

{001}<100> Orientierung {110}<111> Gleitung

-2

 $\sigma_{11} / \tau_{mit}$ 

symmetric part

$$m_{kl}^{\text{sym,s}} = \frac{1}{2} \left( a_{ki}^{c} n_{i}^{s} a_{lj}^{c} b_{j}^{s} + a_{lj}^{c} n_{j}^{s} a_{ki}^{c} b_{i}^{s} \right)$$

yield surface (active systems)

$$m_{\rm kl}^{\rm \, sym,s=aktiv}\sigma_{\rm kl}=\sigma_{\rm aufg}^{\rm s}=\tau_{\rm krit,(+)}^{\rm \, s=aktiv}$$

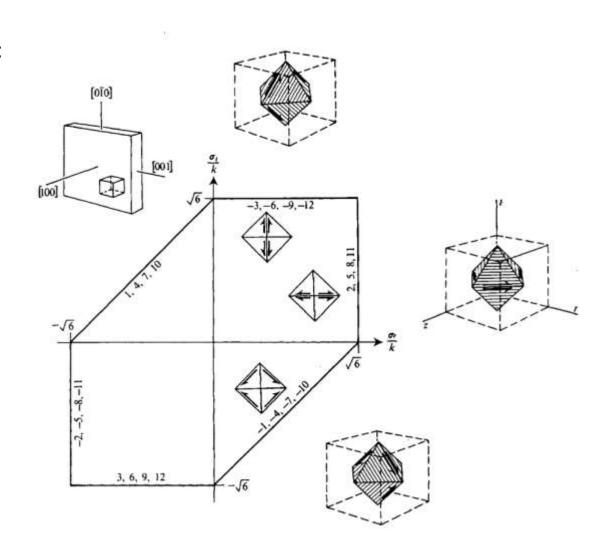
$$m_{
m kl}^{
m sym,s=aktiv}\sigma_{
m kl}=\sigma_{
m aufg}^{
m s}= au_{
m krit,(-)}^{
m s=aktiv}$$

(non-active systems)

$$m_{
m kl}^{
m \, sym,s=inaktiv} \sigma_{
m kl} = \sigma_{
m \, aufg}^{
m s} < au_{
m krit,(\pm)}^{
m s=inaktiv}$$



Cube texture component: (001)[100]



## Plasticity based on dislocation motion

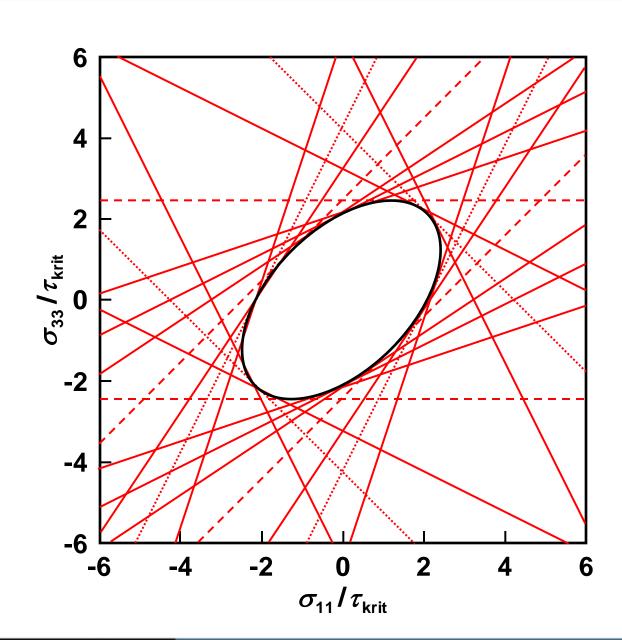


## Active slip system:

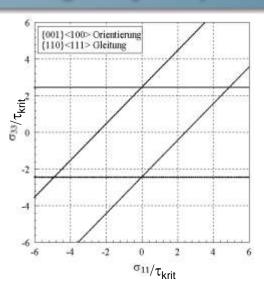
$$\tau^{\alpha} = \tau_{\rm crit}$$

with 
$$\boldsymbol{\tau}^{\alpha} \approx \boldsymbol{T}_{\mathrm{e}} \cdot \boldsymbol{S}_{\mathrm{0}}^{\ \alpha}$$
  $\boldsymbol{S}_{\mathrm{0}}^{\ \alpha} = \boldsymbol{m}_{\mathrm{0}}^{\ \alpha} \otimes \boldsymbol{n}_{\mathrm{0}}^{\ \alpha}$ 

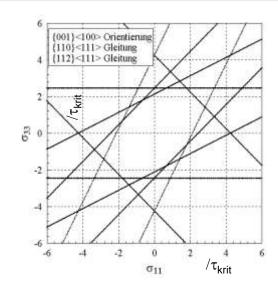
bcc 48 slip systems orientation {001}<100>



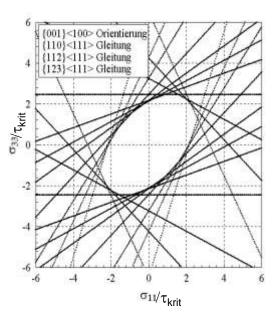




FCC, BCC 12 systems section



BCC 24 systems section



BCC 48 systems section

yield surface, bcc

single crystal, bcc, (001)[100]

## Macroscopic – empiricial yield criteria



Yield criterion: determine the critical stress required to cause permanent deformation

Many different macroscopic yield criteria

 $\sigma_{ij}$  stress acting on a solid  $\sigma$ 1,  $\sigma$ 2,  $\sigma$ 3 principal values of stress tensor Y yield stress of the material in uniaxial tension

$$(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 = \text{constant}$$

$$\frac{\sigma_2}{\gamma}$$

$$\text{von Mises}$$

$$\frac{\sigma_1}{\gamma}$$

$$(\sigma_1 - \sigma_3) = Y$$

$$(\sigma_1 > \sigma_2 > \sigma_3)$$

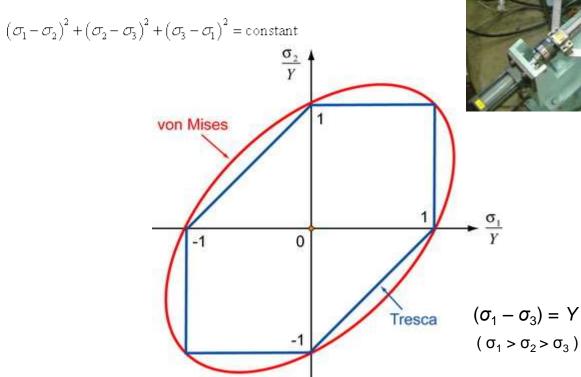
## Macroscopic yield criteria



Yield criterion: determine the critical stress required to cause permanent deformation

Many different macroscopic yield criteria

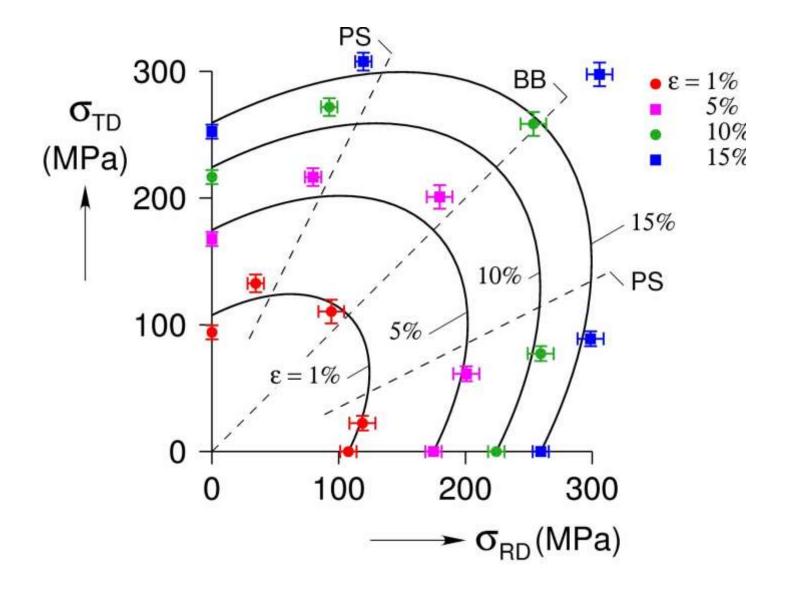
 $\sigma_{ij}$  stress acting on a solid  $\sigma$ 1,  $\sigma$ 2,  $\sigma$ 3 principal values of stress tensor Y yield stress of the material in uniaxial tension





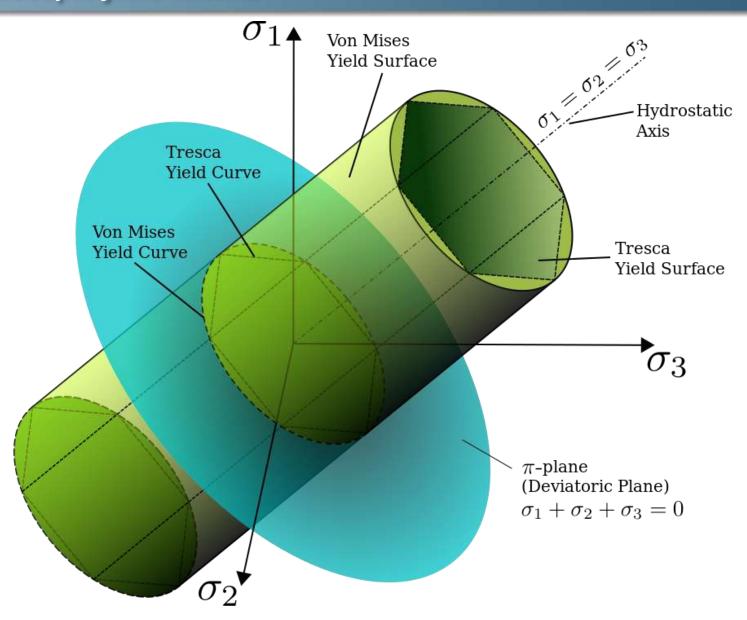






## Macroscopic yield criteria







How does that work for bicrystals?

Two extreme cases :

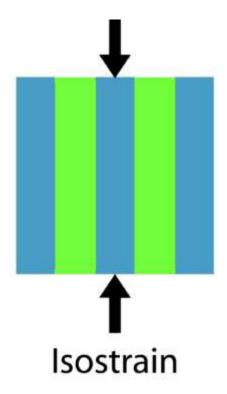
iso-strain (Taylor)

iso-stress (Schmid)

## Iso-stress and iso-strain: general approach



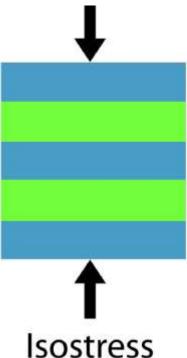




$$\varepsilon = \varepsilon_s = \varepsilon_d$$

$$\sigma = \sigma_s + \sigma_d$$

Displacement continuity across layers



$$\varepsilon = \varepsilon_s + \varepsilon_d$$

$$\sigma = \sigma_s = \sigma_d$$

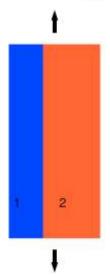
Stress continuity across layers

## Iso-stress and iso-strain: Elastic approach: composite stiffness





## Bounding Case - Isostrain



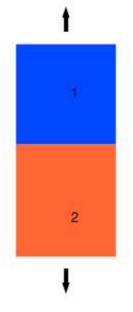
$$\begin{split} & \epsilon_{1} = \epsilon_{2} = \epsilon_{tot} \\ & \sigma_{1} = E_{1} \epsilon_{1} = E_{1} \epsilon_{tot} \quad ; \quad \sigma_{2} = E_{2} \epsilon_{2} = E_{2} \epsilon_{tot} \\ & P_{1} = A_{1} \sigma_{1} = A_{1} E_{1} \epsilon_{tot} \quad ; \quad P_{2} = A_{2} \sigma_{2} = A_{2} E_{2} \epsilon_{tot} \\ & P_{tot} = P_{1} + P_{2} = \epsilon_{tot} (A_{1} E_{1} + A_{2} E_{2}) \\ & \sigma_{tot} = \frac{P_{tot}}{A_{1} + A_{2}} = \epsilon_{tot} \left( \frac{A_{1}}{A_{1} + A_{2}} E_{1} + \frac{A_{2}}{A_{1} + A_{2}} E_{2} \right) \\ & \sigma_{tot} = (f_{1} E_{1} + f_{2} E_{2}) \epsilon_{tot} \end{split}$$

$$E_{tot} = f_{1} E_{1} + f_{2} E_{2}$$

P, P are the loads on 1 and 2.

f,, f are the volume fractions of 1 and 2.

## Bounding Case - Isostress



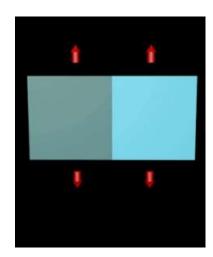
$$\begin{split} &\sigma_{1} = \sigma_{2} = \sigma_{tot} \\ &\sigma_{1} = E_{1} \epsilon_{1} \quad ; \quad \sigma_{2} = E_{2} \epsilon_{2} \\ &\epsilon_{tot} = f_{1} \epsilon_{1} + f_{2} \epsilon_{2} = f_{1} \frac{\sigma_{tot}}{E_{1}} + f_{2} \frac{\sigma_{tot}}{E_{2}} \end{split}$$

$$E = \frac{\sigma_{tot}}{\epsilon_{tot}} = \frac{1}{\frac{f_1}{\epsilon_1} + \frac{f_2}{\epsilon_2}} = \frac{E_1 E_2}{f_1 E_2 + f_2 E_1}$$

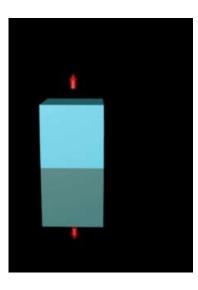




iso-strain (Taylor-model)



iso-stress (Sachs-model)



## Iso-stress and iso-strain for polycrystals





#### Sachs Model (previous lecture on single crystal):

- All grains with aggregate or polycrystal experience the same state of stress;
- Equilibrium condition across the grain boundaries satisfied;
- Compatibility conditions between the grains violated, thus, finite strains will lead to gaps and overlaps between grains;
- Generally most successful for single crystal deformation with stress boundary conditions on each grain.



#### Taylor Model (this lecture):

- All single-crystal grains within the aggregate experience the same state of deformation (strain);
- Equilibrium condition across the grain boundaries violated, because the vertex stress states required to activate multiple slip in each grain vary from grain to grain;
- Compatibility conditions between the grains satisfied;
- Generally most successful for polycrystals with strain boundary conditions on each grain.





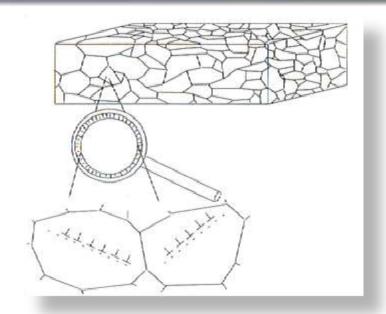


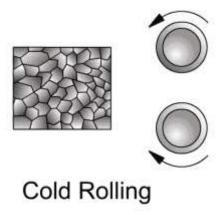
Taylor model for the mechanics of polycrystals

## **The Taylor Model**







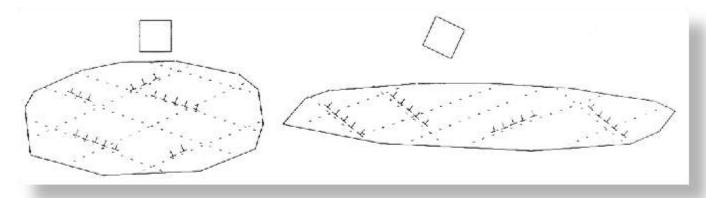


$$\varepsilon_{ij} = \frac{1}{2} \sum_{s=1}^{5} \left( n_i^s b_j^s + n_j^s b_i^s \right) \gamma^s$$



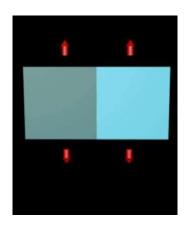


$$\varepsilon_{ij} = \frac{1}{2} \sum_{s=1}^{5} \left( n_i^s b_j^s + n_j^s b_i^s \right) \gamma^s$$



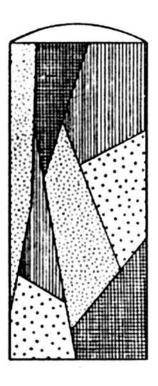
## plastic spin from polar decomposition

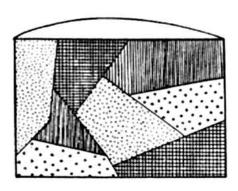
$$\dot{\omega}_{ij}^{K} = W_{ij}^{K} = \frac{1}{2} (\dot{u}_{i,j}^{K} - \dot{u}_{j,i}^{K}) = \sum_{s=1}^{N} m_{ij}^{\text{asym},s} \dot{\gamma}^{s}$$







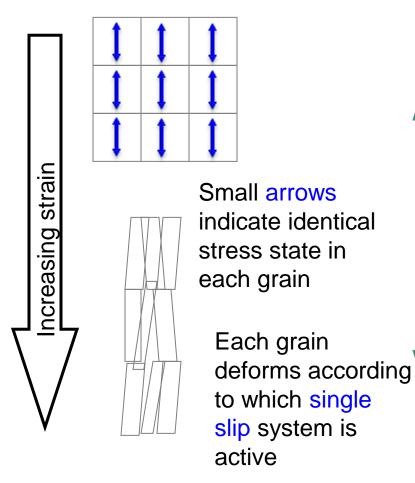




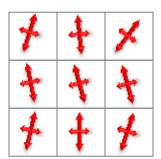
## The Taylor Model – comparison to Sachs model



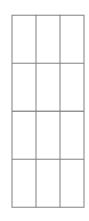
#### **External Stress**



#### **External Strain**



Small arrows indicate variable stress state in each grain



Multiple slip (with 5 or more systems) in each grain satisfies the externally imposed strain, D

## The Taylor Model – comparison to Sachs model



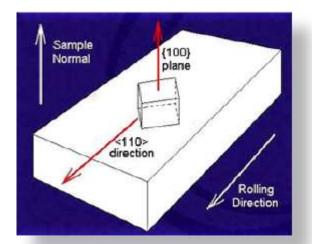
$$\begin{bmatrix} D_2 \\ D_3 \\ D_4 \\ D_5 \\ D_6 \end{bmatrix} = \begin{bmatrix} m_{22}^{(1)} & m_{22}^{(2)} & m_{22}^{(3)} & m_{22}^{(4)} & m_{22}^{(5)} \\ m_{22}^{(1)} & m_{22}^{(2)} & m_{22}^{(3)} & m_{22}^{(3)} & m_{22}^{(5)} \\ m_{33}^{(1)} & m_{33}^{(2)} & m_{33}^{(2)} & m_{33}^{(3)} & m_{33}^{(4)} & m_{33}^{(5)} \\ (m_{23}^{(1)} + m_{32}^{(1)})(m_{23}^{(2)} + m_{32}^{(2)})(m_{23}^{(3)} + m_{32}^{(3)})(m_{23}^{(4)} + m_{32}^{(4)})(m_{23}^{(5)} + m_{32}^{(5)}) \\ (m_{13}^{(1)} + m_{31}^{(1)})(m_{13}^{(2)} + m_{31}^{(2)})(m_{13}^{(3)} + m_{31}^{(3)})(m_{13}^{(4)} + m_{31}^{(4)})(m_{13}^{(5)} + m_{31}^{(5)}) \\ (m_{12}^{(1)} + m_{21}^{(1)})(m_{12}^{(2)} + m_{21}^{(2)})(m_{12}^{(3)} + m_{21}^{(3)})(m_{12}^{(4)} + m_{21}^{(4)})(m_{12}^{(5)} + m_{21}^{(5)}) \end{bmatrix} \begin{bmatrix} d\gamma_1 \\ d\gamma_2 \\ d\gamma_3 \\ d\gamma_4 \\ d\gamma_5 \end{bmatrix}$$

$$\begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \\ \tau_4 \\ \tau_5 \end{bmatrix} = \begin{bmatrix} m_{11}^{(1)} m_{22}^{(1)} m_{33}^{(1)} (m_{23}^{(1)} + m_{32}^{(1)}) (m_{13}^{(1)} + m_{31}^{(1)}) (m_{12}^{(1)} + m_{21}^{(1)}) \\ m_{11}^{(2)} m_{22}^{(2)} m_{33}^{(2)} (m_{23}^{(2)} + m_{32}^{(2)}) (m_{13}^{(2)} + m_{31}^{(2)}) (m_{12}^{(2)} + m_{21}^{(2)}) \\ m_{11}^{(3)} m_{22}^{(3)} m_{33}^{(3)} (m_{23}^{(3)} + m_{32}^{(3)}) (m_{13}^{(3)} + m_{31}^{(3)}) (m_{12}^{(3)} + m_{21}^{(3)}) \\ m_{11}^{(4)} m_{22}^{(4)} m_{33}^{(4)} (m_{23}^{(4)} + m_{32}^{(4)}) (m_{13}^{(4)} + m_{31}^{(4)}) (m_{12}^{(4)} + m_{21}^{(4)}) \\ m_{11}^{(5)} m_{22}^{(5)} m_{33}^{(5)} (m_{23}^{(5)} + m_{32}^{(5)}) (m_{13}^{(5)} + m_{31}^{(5)}) (m_{12}^{(5)} + m_{21}^{(5)}) \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix}$$

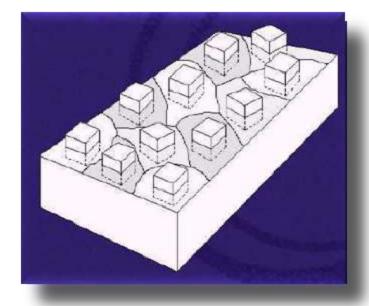
## Crystal rotations under heterogeneous constraints







Grains in polycrystals do NOT experience the same boundary conditions.



Differentiate between GLOBAL bounday conditions (tool, process) and the LOCAL (micromechanical) boundary conditions. The latter are influenced by grain-to-grain interactions and local inhomogeneity.



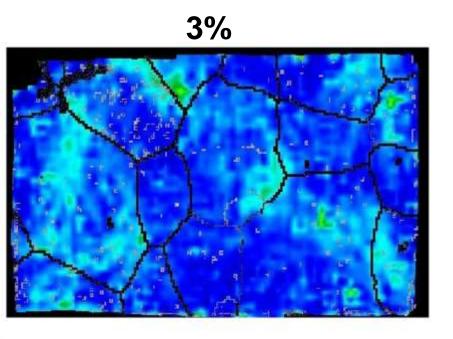


## Examples

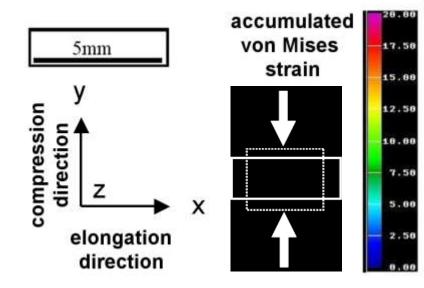
## Homogeneity and boundary conditions at grain scale







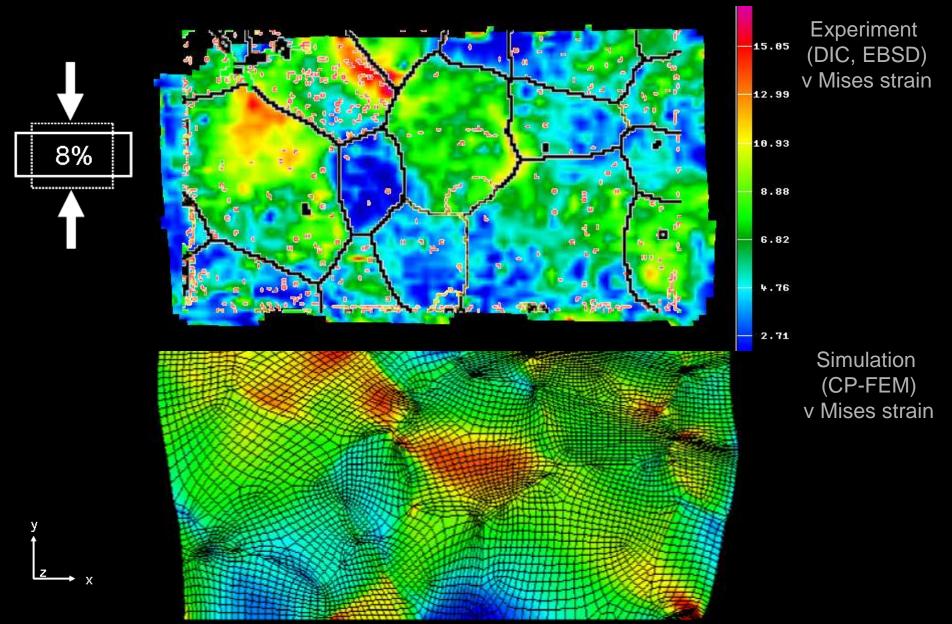




Raabe et al. Acta Mater. 49 (2001) 3433

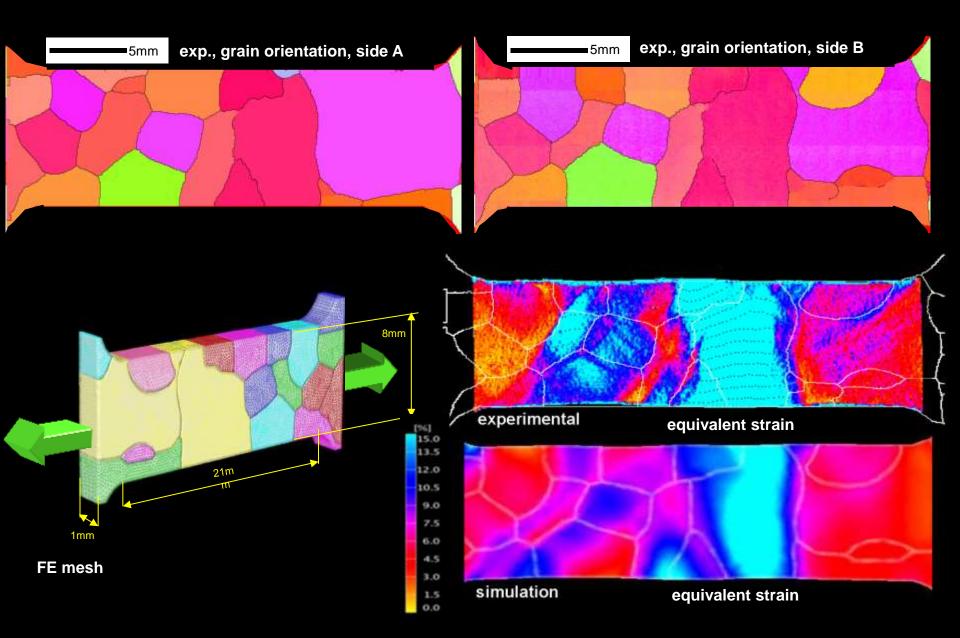
## Crystal Mechanics FEM, grain scale mechanics (2D)





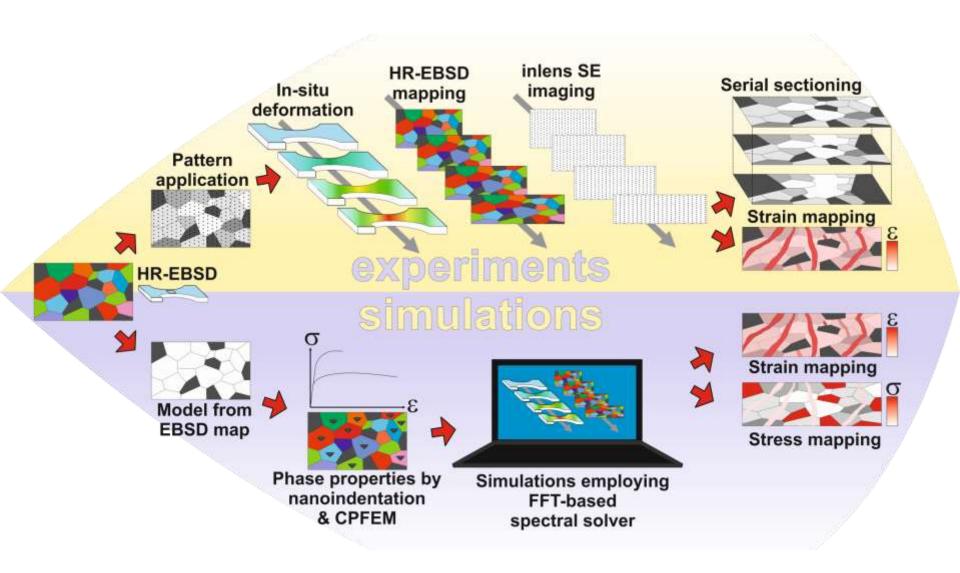
## Crystal plasticity FEM, grain scale mechanics (3D AI)





## **ICME: Integrated Computational Materials Engineering**

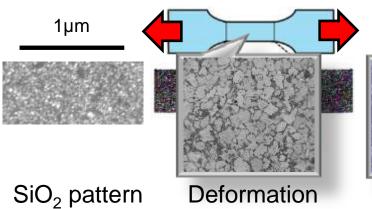


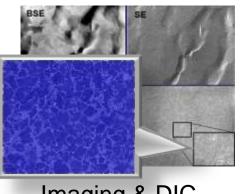


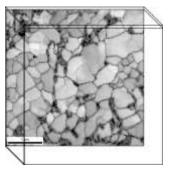
## ICME applied to dual phase steel

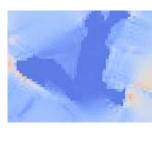












Imaging & DIC

Sectioning

Strain map





## **Experiments**

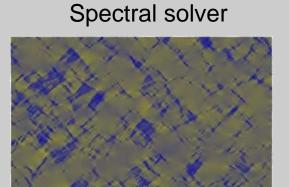
### **Simulations**

Digital model

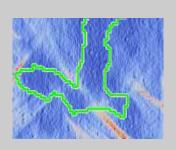






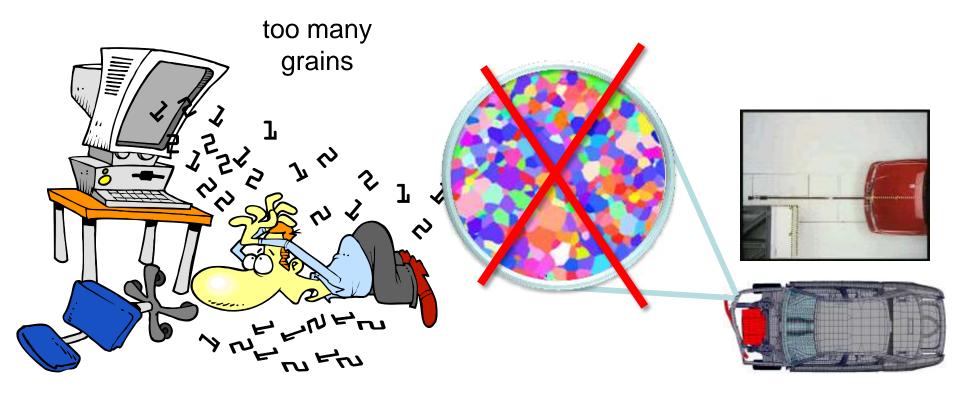


Strain map & stress map



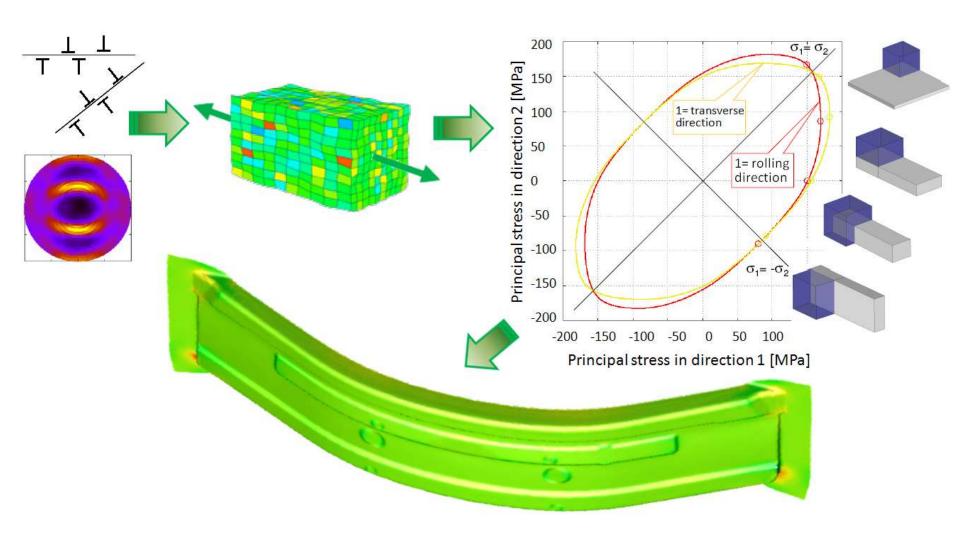
## **Crystal plasticity FEM for large scale forming predictions**





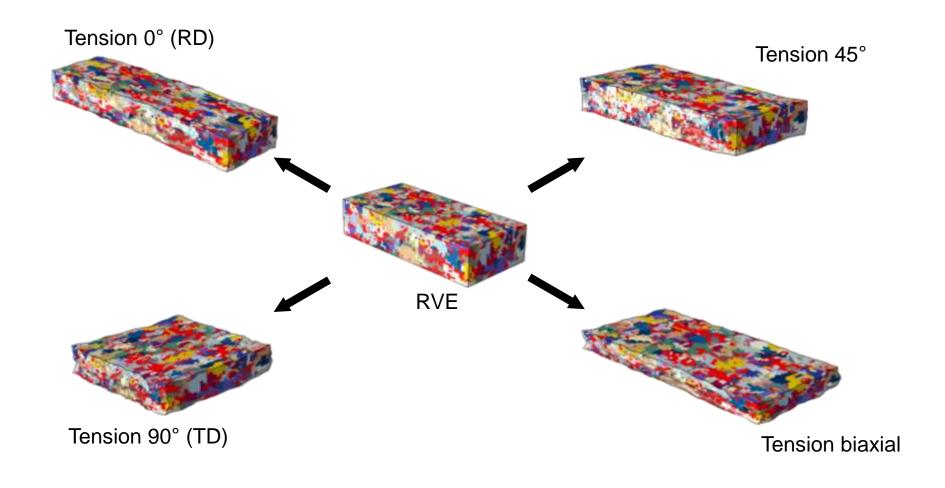


## Numerical Laboratory: From CPFEM to yield surface (engineering)





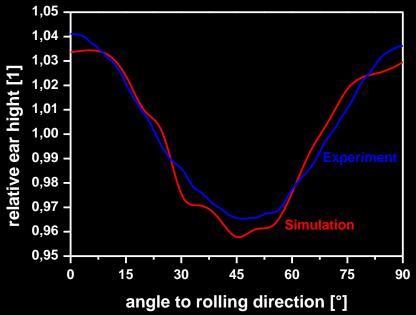


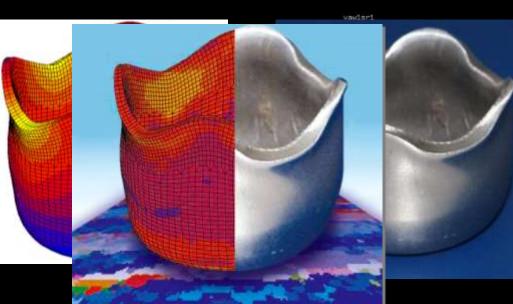


## Texture component crystal plasticity FEM for large scale forming



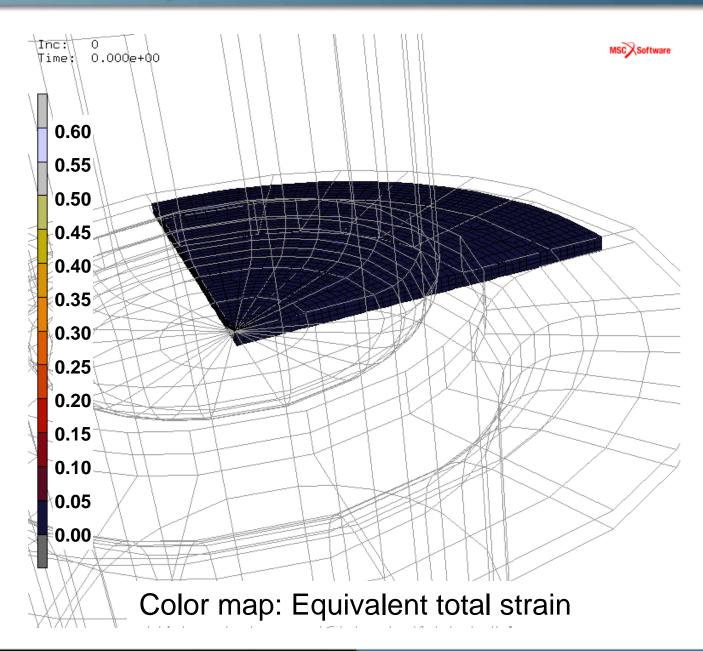






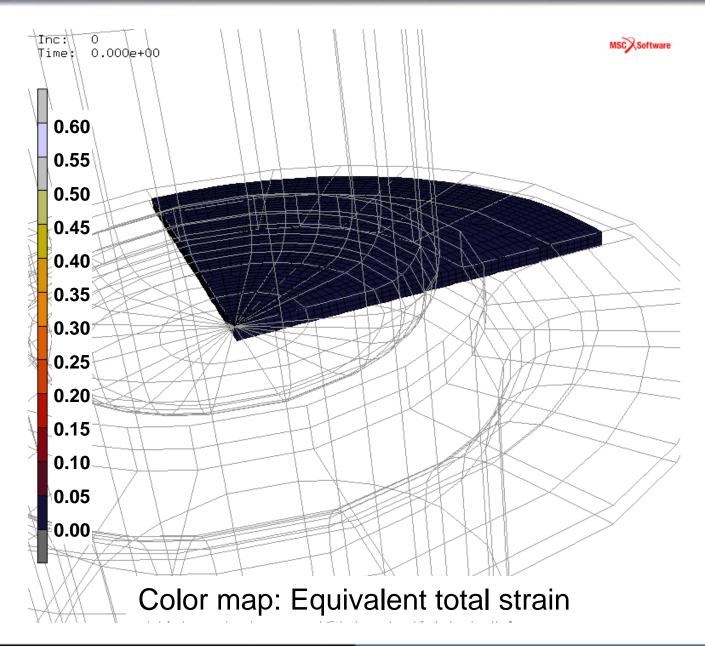
## Simulation result: Taylor model





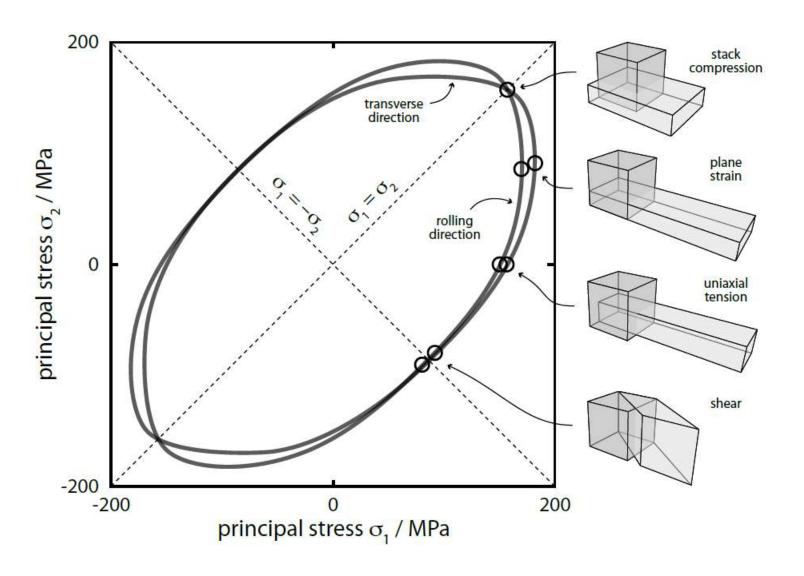
## Simulation result: RGC scheme









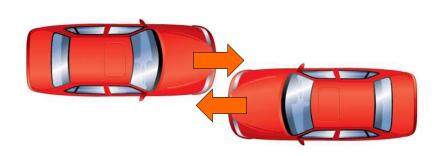


## Mechanical properties: ... for which structural component?

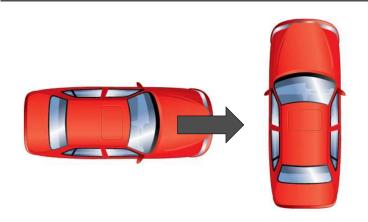


## **Component-specific property mix**

Front crash ⇒ Energy absorption

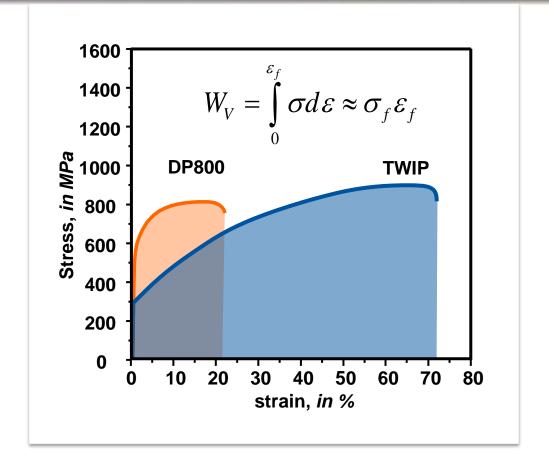


Side crash ⇒ Strength



## Strain rate 800/s: compare TWIP steel to DP800





**Awareness of impact situation** 

## Düsseldorf Advanced MAterial Simulation Kit, DAMASK







Düsseldorf Advanced Material Simulation Kit

Freeware, GPL 3



Crystal plasticity & phase field:

Mechanics, damage, phase transformation, diffusion

- > 15 years of development
- > 50 man years of expertise
- > 50.000 lines of code
- Pre- and post-processing

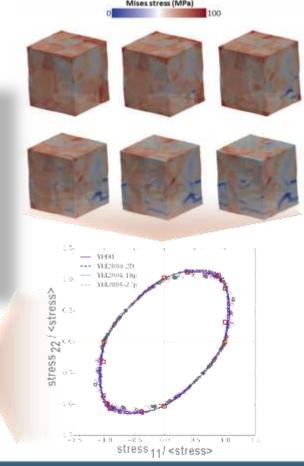
Blends with MSC.Marc and Abaqus

Standalone (FFT) spectral solver

Many user groups

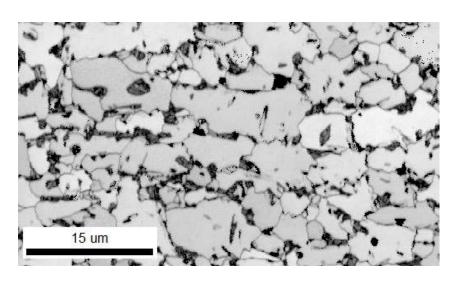
http://DAMASK.mpie.de





## **Real 3D Microstructure**





Average grain size:  $5~\mu m$ 

EBSD step size: 0,2 μm

EBSD scan size:  $20 \times 70 \mu m$ 

Target polished thickness: 0,15 μm

Total slices number: 22

Marker lines act as a realignment reference

Experiment by Dayong An, MPIE





